# Global surface of section and Hamiltonian dynamics on 2-disk

Jun Zhang

CRM - Université de Montréal

June 16, 2020

The goal of this talk is to prove the following result.

#### Theorem (Abbondandolo-Bramham-Hryniewicz-Salomão, 2018)

There exists a contact form  $\alpha$  on  $S^3$  such that

$$T_{\min}(\alpha)^2 > \operatorname{vol}_{\alpha \wedge d\alpha}(S^3)$$

where  $T_{\min}(\alpha)$  is the minimal period of the closed Reeb orbits.

The goal of this talk is to prove the following result.

#### Theorem (Abbondandolo-Bramham-Hryniewicz-Salomão, 2018)

There exists a contact form  $\alpha$  on  $S^3$  such that

$$T_{\min}(\alpha)^2 > \operatorname{vol}_{\alpha \wedge d\alpha}(S^3)$$

where  $T_{\min}(\alpha)$  is the minimal period of the closed Reeb orbits.

#### Remark

(1) The conclusion above does *not* hold for  $\alpha=\alpha_0$ , the standard contact structure of  $S^3$ . In fact,  $T_{\min}=\pi$  and  $\operatorname{vol}_{\alpha\wedge d\alpha}(S^3)=\pi^2$  (Exercise).

The goal of this talk is to prove the following result.

#### Theorem (Abbondandolo-Bramham-Hryniewicz-Salomão, 2018)

There exists a contact form  $\alpha$  on  $S^3$  such that

$$T_{\min}(\alpha)^2 > \operatorname{vol}_{\alpha \wedge d\alpha}(S^3)$$

where  $T_{\min}(\alpha)$  is the minimal period of the closed Reeb orbits.

#### Remark

(1) The conclusion above does *not* hold for  $\alpha=\alpha_0$ , the standard contact structure of  $S^3$ . In fact,  $T_{\min}=\pi$  and  $\operatorname{vol}_{\alpha\wedge d\alpha}(S^3)=\pi^2$  (Exercise). (2) The  $\alpha$  constructed in Theorem above satisfies many other nice properties, but we will not emphasize those in this talk.

• Denote by  $\mathbb D$  the (closed) unit disk of  $\mathbb C$ , with the standard symplectic form  $\omega=dx\wedge dy$  and primitive  $\lambda=\frac{1}{2}(xdy-ydx)$ .

- Denote by  $\mathbb D$  the (closed) unit disk of  $\mathbb C$ , with the standard symplectic form  $\omega=dx\wedge dy$  and primitive  $\lambda=\frac{1}{2}(xdy-ydx)$ .
- Let  $\operatorname{Ham}_c(\mathring{\mathbb{D}},\omega)$  denote the compactly supported Hamiltonian diffeomorphism group on  $(\mathring{\mathbb{D}},\omega)$ . There is **Calabi homomorphism** denoted by  $\operatorname{Cal}:\operatorname{Ham}_c(\mathring{\mathbb{D}},\omega)\to\mathbb{R}$  and defined by

$$\operatorname{Cal}(\phi_H^1) = 2 \int_{[0,1] \times \mathbb{D}} H(t,z) dt \wedge \omega.$$

- Denote by  $\mathbb D$  the (closed) unit disk of  $\mathbb C$ , with the standard symplectic form  $\omega=dx\wedge dy$  and primitive  $\lambda=\frac{1}{2}(xdy-ydx)$ .
- Let  $\operatorname{Ham}_c(\mathring{\mathbb{D}},\omega)$  denote the compactly supported Hamiltonian diffeomorphism group on  $(\mathring{\mathbb{D}},\omega)$ . There is **Calabi homomorphism** denoted by  $\operatorname{Cal}:\operatorname{Ham}_c(\mathring{\mathbb{D}},\omega)\to\mathbb{R}$  and defined by

$$\operatorname{Cal}(\phi_H^1) = 2 \int_{[0,1] \times \mathbb{D}} H(t,z) dt \wedge \omega.$$

• Strategy goes as follows.

$$\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega) \leadsto \begin{array}{l} \beta \text{ a contact form} \\ \text{ on solid torus } \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z} \\ \text{ (due to Bramham)} \end{array} \leadsto \begin{array}{l} \alpha \text{ a contact form} \\ \text{ on } S^3 \text{ satisfying (1)} \end{array}$$

$$\operatorname{vol}_{\alpha \wedge d\alpha}(S^3) = \pi^2 + \operatorname{Cal}(\phi). \tag{1}$$



- Denote by  $\mathbb D$  the (closed) unit disk of  $\mathbb C$ , with the standard symplectic form  $\omega=dx\wedge dy$  and primitive  $\lambda=\frac{1}{2}(xdy-ydx)$ .
- Let  $\operatorname{Ham}_c(\mathring{\mathbb{D}},\omega)$  denote the compactly supported Hamiltonian diffeomorphism group on  $(\mathring{\mathbb{D}},\omega)$ . There is **Calabi homomorphism** denoted by  $\operatorname{Cal}:\operatorname{Ham}_c(\mathring{\mathbb{D}},\omega)\to\mathbb{R}$  and defined by

$$\operatorname{Cal}(\phi_H^1) = 2 \int_{[0,1] \times \mathbb{D}} H(t,z) dt \wedge \omega.$$

• Strategy goes as follows.

$$\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega) \leadsto \begin{array}{l} \beta \text{ a contact form} \\ \text{ on solid torus } \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z} \\ \text{ (due to Bramham)} \end{array} \leadsto \begin{array}{l} \alpha \text{ a contact form} \\ \text{ on } S^3 \text{ satisfying (1)} \end{array}$$

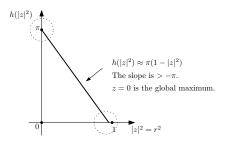
$$\operatorname{vol}_{\alpha \wedge d\alpha}(S^3) = \pi^2 + \operatorname{Cal}(\phi). \tag{1}$$

Moreover, this  $\phi$  is special since  $Cal(\phi) < 0$  but  $T_{min}(\alpha) \ge \pi$ .

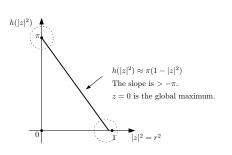


## Radial symmetric Hamiltonian on $\mathbb D$

• Consider the autonomous Hamiltonian  $H: \mathbb{D} \to \mathbb{R}$  such that  $H(z) = h(|z|^2)$  where  $h: [0,1] \to \mathbb{R}$  is defined in the following picture (where circle regions are smoothed),



• Consider the autonomous Hamiltonian  $H: \mathbb{D} \to \mathbb{R}$  such that  $H(z) = h(|z|^2)$  where  $h: [0,1] \to \mathbb{R}$  is defined in the following picture (where circle regions are smoothed),



(1) 
$$\phi_H^1(z) = e^{-2h'(|z|^2)i}z$$
.

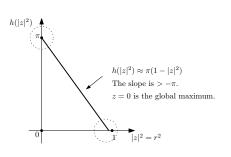
(2) 
$$\operatorname{Cal}(\phi_H^1) \approx \pi^2$$
.

In general,

$$\operatorname{Cal}(\phi_H^1) = 4\pi \int_0^1 rh(r^2) dr.$$

## Radial symmetric Hamiltonian on $\mathbb D$

• Consider the autonomous Hamiltonian  $H: \mathbb{D} \to \mathbb{R}$  such that  $H(z) = h(|z|^2)$  where  $h: [0,1] \to \mathbb{R}$  is defined in the following picture (where circle regions are smoothed),



(Exercise)  
(1) 
$$\phi_H^1(z) = e^{-2h'(|z|^2)i}z$$
.

(2) 
$$\operatorname{Cal}(\phi_H^1) \approx \pi^2$$
.

In general,

$$\operatorname{Cal}(\phi_H^1) = 4\pi \int_0^1 rh(r^2) dr.$$

• Observe that fixed points lie in neighborhood of  $\partial \mathbb{D}$  and z = 0.



#### Action function

Given a radial symmetric Hamiltonian function  $H: \mathbb{D} \to \mathbb{R}$ , where  $H(z) = h(|z|^2)$ . Consider **action function**  $\sigma: \mathbb{D} \to \mathbb{R}$  defined by  $\sigma(z) = h(|z|^2) - |z|^2 h'(|z|^2)$ .

\*This is the "y-intercept" of the tangent line along the graph of  $h(|z|^2)$ .

#### Action function

Given a radial symmetric Hamiltonian function  $H: \mathbb{D} \to \mathbb{R}$ , where  $H(z) = h(|z|^2)$ . Consider **action function**  $\sigma: \mathbb{D} \to \mathbb{R}$  defined by  $\sigma(z) = h(|z|^2) - |z|^2 h'(|z|^2).$ 

\*This is the "y-intercept" of the tangent line along the graph of  $h(|z|^2)$ .

#### Remark

For a general  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega)$ , action function is defined by  $\sigma(z) = \int_{\{t \to \phi_t(z)\}} \lambda + \int_0^1 H_t(\phi_t(z)) dt$ . (Exercise:  $\phi^* \lambda - \lambda = d\sigma$ .)

#### Action function

Given a radial symmetric Hamiltonian function  $H: \mathbb{D} \to \mathbb{R}$ , where  $H(z) = h(|z|^2)$ . Consider **action function**  $\sigma: \mathbb{D} \to \mathbb{R}$  defined by  $\sigma(z) = h(|z|^2) - |z|^2 h'(|z|^2)$ .

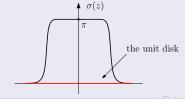
\*This is the "y-intercept" of the tangent line along the graph of  $h(|z|^2)$ .

#### Remark

For a general  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega)$ , action function is defined by  $\sigma(z) = \int_{\{t \to \phi_t(z)\}} \lambda + \int_0^1 H_t(\phi_t(z)) dt$ . (Exercise:  $\phi^* \lambda - \lambda = d\sigma$ .)

#### Example

For H chosen earlier, action function is the following graph.



• Consider  $\tau(z) = \sigma(z) + \pi$ .

• Consider  $\tau(z) = \sigma(z) + \pi$ . Twisting map  $t : \mathbb{D} \times \mathbb{R} \to \mathbb{D} \times \mathbb{R}$ 

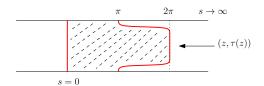
$$t:(z,s)\to(\phi(z),s-\tau(z))$$

is a free  $\mathbb{Z}$ -action, denoted by  $\sim$ . Denote by  $M:=(\mathbb{D}\times\mathbb{R})/\sim$ .

• Consider  $\tau(z) = \sigma(z) + \pi$ . Twisting map  $t : \mathbb{D} \times \mathbb{R} \to \mathbb{D} \times \mathbb{R}$ 

$$t:(z,s)\to(\phi(z),s-\tau(z))$$

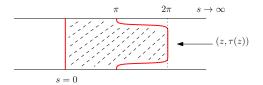
is a free  $\mathbb{Z}$ -action, denoted by  $\sim$ . Denote by  $M:=(\mathbb{D}\times\mathbb{R})/\sim$ . More explicitly, observe that  $(z,\tau(z))$  is identified with  $(\phi(z),0)$ , then M is like a solid torus in the shaded region after identifying the red sides.



• Consider  $\tau(z) = \sigma(z) + \pi$ . Twisting map  $t : \mathbb{D} \times \mathbb{R} \to \mathbb{D} \times \mathbb{R}$ 

$$t:(z,s)\to(\phi(z),s-\tau(z))$$

is a free  $\mathbb{Z}$ -action, denoted by  $\sim$ . Denote by  $M:=(\mathbb{D}\times\mathbb{R})/\sim$ . More explicitly, observe that  $(z,\tau(z))$  is identified with  $(\phi(z),0)$ , then M is like a solid torus in the shaded region after identifying the red sides.

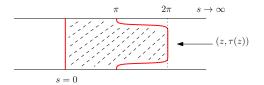


• Observe that  $t^*(\lambda + ds) = \lambda + ds$  (Exercise). Therefore, M admits a well-defined contact form denoted by  $\eta$ .

• Consider  $\tau(z) = \sigma(z) + \pi$ . Twisting map  $t : \mathbb{D} \times \mathbb{R} \to \mathbb{D} \times \mathbb{R}$ 

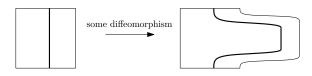
$$t:(z,s)\to(\phi(z),s-\tau(z))$$

is a free  $\mathbb{Z}$ -action, denoted by  $\sim$ . Denote by  $M:=(\mathbb{D}\times\mathbb{R})/\sim$ . More explicitly, observe that  $(z,\tau(z))$  is identified with  $(\phi(z),0)$ , then M is like a solid torus in the shaded region after identifying the red sides.

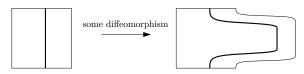


- Observe that  $t^*(\lambda + ds) = \lambda + ds$  (Exercise). Therefore, M admits a well-defined contact form denoted by  $\eta$ .
- Near the boundary,  $M = U \times \mathbb{R}/\pi\mathbb{Z}$  where U is a neighborhood of  $\partial \mathbb{D}$  and  $\eta = \lambda + ds$ .

The desired contact form  $\beta$  is on the solid torus  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . There exists some diffeomorphism  $f: \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z} \to M$  as in the following picture.

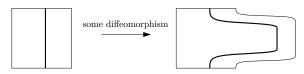


The desired contact form  $\beta$  is on the solid torus  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . There exists some diffeomorphism  $f: \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z} \to M$  as in the following picture.



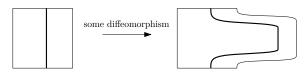
We need extra care to make sure that the area of each slice is preserved. Then define  $\beta = f^*\eta$ .

The desired contact form  $\beta$  is on the solid torus  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . There exists some diffeomorphism  $f: \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z} \to M$  as in the following picture.



We need extra care to make sure that the area of each slice is preserved. Then define  $\beta = f^*\eta$ . Still, near the boundary,  $\beta = \lambda + ds$  (since f is the identity near the boundary).

The desired contact form  $\beta$  is on the solid torus  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . There exists some diffeomorphism  $f: \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z} \to M$  as in the following picture.



We need extra care to make sure that the area of each slice is preserved. Then define  $\beta = f^*\eta$ . Still, near the boundary,  $\beta = \lambda + ds$  (since f is the identity near the boundary).

#### Example

One can compute that  $\operatorname{vol}_{\beta \wedge d\beta}(\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}) = \operatorname{vol}_{\eta \wedge d\eta} M \simeq 2\pi^2$ . Then, up to small gaps, we get

$$\operatorname{vol}_{\beta \wedge d\beta}(\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}) = \pi^2 + \operatorname{Cal}(\phi_H^1).$$

• Thomas taught us that  $S^3$  is not far from  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ .

• Thomas taught us that  $S^3$  is not far from  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . Denote by C the circle  $\{|z_1|=1,\ z_2=0\}$  (which is a closed Reeb orbit of  $\alpha_0$ ), the morphism  $g: \mathring{\mathbb{D}} \times \mathbb{R}/\pi\mathbb{Z} \to S^3 \backslash C$  defined by

$$g(r, \theta, s) = \left(re^{i(\theta+2s)}, \sqrt{1-r^2}e^{2is}\right)$$

is a diffeomorphism, which extends to map  $\partial \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$  to the circle C.

• Thomas taught us that  $S^3$  is not far from  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . Denote by C the circle  $\{|z_1|=1,\ z_2=0\}$  (which is a closed Reeb orbit of  $\alpha_0$ ), the morphism  $g: \mathring{\mathbb{D}} \times \mathbb{R}/\pi\mathbb{Z} \to S^3 \backslash C$  defined by

$$g(r,\theta,s) = \left(re^{i(\theta+2s)},\sqrt{1-r^2}e^{2is}\right)$$

is a diffeomorphism, which extends to map  $\partial \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$  to the circle C. Moreover,  $g^*\alpha_0 = \lambda + ds$ .

• Thomas taught us that  $S^3$  is not far from  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . Denote by C the circle  $\{|z_1|=1,\ z_2=0\}$  (which is a closed Reeb orbit of  $\alpha_0$ ), the morphism  $g: \mathring{\mathbb{D}} \times \mathbb{R}/\pi\mathbb{Z} \to S^3 \backslash C$  defined by

$$g(r, \theta, s) = \left(re^{i(\theta+2s)}, \sqrt{1-r^2}e^{2is}\right)$$

is a diffeomorphism, which extends to map  $\partial \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$  to the circle C. Moreover,  $g^*\alpha_0 = \lambda + ds$ .

• Define  $\alpha = (g^{-1})^*\beta$  (and extend). Notice that  $\alpha = \alpha_0$  near C.



• Thomas taught us that  $S^3$  is not far from  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . Denote by C the circle  $\{|z_1|=1,\ z_2=0\}$  (which is a closed Reeb orbit of  $\alpha_0$ ), the morphism  $g: \mathring{\mathbb{D}} \times \mathbb{R}/\pi\mathbb{Z} \to S^3 \backslash C$  defined by

$$g(r, \theta, s) = \left(re^{i(\theta+2s)}, \sqrt{1-r^2}e^{2is}\right)$$

is a diffeomorphism, which extends to map  $\partial \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$  to the circle C. Moreover,  $g^*\alpha_0 = \lambda + ds$ .

• Define  $\alpha = (g^{-1})^*\beta$  (and extend). Notice that  $\alpha = \alpha_0$  near C.

#### Proposition

For each fixed  $s \in \mathbb{R}/\pi\mathbb{Z}$ , the image  $\operatorname{im}(g|_{\mathbb{D}\times\{s\}})$  is a disk-like global surface of section (with boundary C) in  $S^3$ .



• Thomas taught us that  $S^3$  is not far from  $\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$ . Denote by C the circle  $\{|z_1|=1,\ z_2=0\}$  (which is a closed Reeb orbit of  $\alpha_0$ ), the morphism  $g: \mathring{\mathbb{D}} \times \mathbb{R}/\pi\mathbb{Z} \to S^3 \backslash C$  defined by

$$g(r,\theta,s) = \left(re^{i(\theta+2s)}, \sqrt{1-r^2}e^{2is}\right)$$

is a diffeomorphism, which extends to map  $\partial \mathbb{D} \times \mathbb{R}/\pi\mathbb{Z}$  to the circle C. Moreover,  $g^*\alpha_0 = \lambda + ds$ .

• Define  $\alpha = (g^{-1})^*\beta$  (and extend). Notice that  $\alpha = \alpha_0$  near C.

#### Proposition

For each fixed  $s \in \mathbb{R}/\pi\mathbb{Z}$ , the image  $\operatorname{im}(g|_{\mathbb{D}\times\{s\}})$  is a disk-like global surface of section (with boundary C) in  $S^3$ .

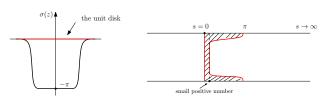
•  $\operatorname{vol}_{\alpha \wedge d\alpha}(S^3) = \operatorname{vol}_{\beta \wedge d\beta}(\mathbb{D} \times \mathbb{R}/\pi\mathbb{Z})$ , which implies the volume-Calabi equation (1). Moreover,  $T_{\min}(\alpha) = \pi$  (Exercise).



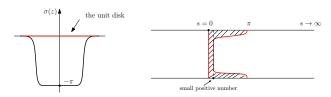
• So far, we have seen an example that some  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega)$  results in a contact 1-form  $\alpha$  on  $S^3$  which can satisfy the volume-Calabi equation (1) and  $T_{\min}(\alpha) = \pi$ , but unfortunately  $\operatorname{Cal}(\phi) > 0$ .

- So far, we have seen an example that some  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega)$  results in a contact 1-form  $\alpha$  on  $S^3$  which can satisfy the volume-Calabi equation (1) and  $T_{\min}(\alpha) = \pi$ , but unfortunately  $\operatorname{Cal}(\phi) > 0$ .
- A cheap way to achieve  $\operatorname{Cal}(\phi) < 0$  is by considering  $\overline{H} := -H$ . Then  $\operatorname{Cal}(\phi \frac{1}{H}) \approx -\pi^2$ .

- So far, we have seen an example that some  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega)$  results in a contact 1-form  $\alpha$  on  $S^3$  which can satisfy the volume-Calabi equation (1) and  $T_{\min}(\alpha) = \pi$ , but unfortunately  $\operatorname{Cal}(\phi) > 0$ .
- A cheap way to achieve  $\operatorname{Cal}(\phi) < 0$  is by considering  $\overline{H} := -H$ . Then  $\operatorname{Cal}(\phi \frac{1}{H}) \approx -\pi^2$ . In this case, the action function and the resulting Bramham's construction are the following,

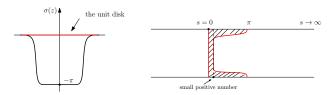


- So far, we have seen an example that some  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega)$  results in a contact 1-form  $\alpha$  on  $S^3$  which can satisfy the volume-Calabi equation (1) and  $T_{\min}(\alpha) = \pi$ , but unfortunately  $\operatorname{Cal}(\phi) > 0$ .
- A cheap way to achieve  $\operatorname{Cal}(\phi) < 0$  is by considering  $\overline{H} := -H$ . Then  $\operatorname{Cal}(\phi \frac{1}{H}) \approx -\pi^2$ . In this case, the action function and the resulting Bramham's construction are the following,



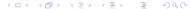
The equation (1) holds, but unfortunately  $T_{\min}(\alpha)$  is very small!

- So far, we have seen an example that some  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega)$  results in a contact 1-form  $\alpha$  on  $S^3$  which can satisfy the volume-Calabi equation (1) and  $T_{\min}(\alpha) = \pi$ , but unfortunately  $\operatorname{Cal}(\phi) > 0$ .
- A cheap way to achieve  $\operatorname{Cal}(\phi) < 0$  is by considering  $\overline{H} := -H$ . Then  $\operatorname{Cal}(\phi \frac{1}{H}) \approx -\pi^2$ . In this case, the action function and the resulting Bramham's construction are the following,



The equation (1) holds, but unfortunately  $T_{\min}(\alpha)$  is very small!

• Need a new example to satisfy both  $Cal(\phi) < 0$  and  $T_{min}(\alpha) \ge \pi$ .



# Sinkhole (cf. Usher's Banach-Mazur distance paper)

#### Example

Consider a disk inside  $\mathbb{D}$ , denoted by  $\mathbb{D}_{(z_0,r_0)}=\{|z-z_0|\leq r_0\}$ 

# Sinkhole (cf. Usher's Banach-Mazur distance paper)

#### Example

Consider a disk inside  $\mathbb{D}$ , denoted by  $\mathbb{D}_{(z_0,r_0)} = \{|z-z_0| \le r_0\}$  and an autonomous Hamiltonian compactly supported inside  $\mathring{\mathbb{D}}_{(z_0,r_0)}$  given by, up to smoothing,

$$H(z) = -k \cdot \left(1 - \frac{|z - z_0|^2}{r_0^2}\right)$$
, where  $k > 0$ .

#### Example

Consider a disk inside  $\mathbb{D}$ , denoted by  $\mathbb{D}_{(z_0,r_0)}=\{|z-z_0|\leq r_0\}$  and an autonomous Hamiltonian compactly supported inside  $\mathring{\mathbb{D}}_{(z_0,r_0)}$  given by, up to smoothing,

$$H(z) = -k \cdot \left(1 - \frac{|z - z_0|^2}{r_0^2}\right)$$
, where  $k > 0$ .

• Cal(
$$\phi$$
)  $\approx -k\pi r_0^2$ ;

#### Example

Consider a disk inside  $\mathbb{D}$ , denoted by  $\mathbb{D}_{(z_0,r_0)}=\{|z-z_0|\leq r_0\}$  and an autonomous Hamiltonian compactly supported inside  $\mathring{\mathbb{D}}_{(z_0,r_0)}$  given by, up to smoothing,

$$H(z) = -k \cdot \left(1 - \frac{|z - z_0|^2}{r_0^2}\right)$$
, where  $k > 0$ .

- Cal( $\phi$ )  $\approx -k\pi r_0^2$ ;
- $\sigma(z) = will$  be explained in 5 mins.

#### Example

Consider a disk inside  $\mathbb{D}$ , denoted by  $\mathbb{D}_{(z_0,r_0)}=\{|z-z_0|\leq r_0\}$  and an autonomous Hamiltonian compactly supported inside  $\mathring{\mathbb{D}}_{(z_0,r_0)}$  given by, up to smoothing,

$$H(z) = -k \cdot \left(1 - \frac{|z - z_0|^2}{r_0^2}\right)$$
, where  $k > 0$ .

- Cal $(\phi) \approx -k\pi r_0^2$ ;
- $\sigma(z) = will$  be explained in 5 mins.
- Trick: Fix an  $\omega$ -preserving diffeomorphism  $\psi$  on  $\mathring{\mathbb{D}}$  such that  $\psi(z)=z+z_0$  on  $\mathbb{D}_{(0,r_0)}$ , and consider  $G=H\circ \psi$ .

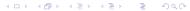


#### Example

Consider a disk inside  $\mathbb{D}$ , denoted by  $\mathbb{D}_{(z_0,r_0)}=\{|z-z_0|\leq r_0\}$  and an autonomous Hamiltonian compactly supported inside  $\mathring{\mathbb{D}}_{(z_0,r_0)}$  given by, up to smoothing,

$$H(z) = -k \cdot \left(1 - \frac{|z - z_0|^2}{r_0^2}\right)$$
, where  $k > 0$ .

- Cal $(\phi) \approx -k\pi r_0^2$ ;
- $\sigma(z) = will$  be explained in 5 mins.
- Trick: Fix an  $\omega$ -preserving diffeomorphism  $\psi$  on  $\mathring{\mathbb{D}}$  such that  $\psi(z)=z+z_0$  on  $\mathbb{D}_{(0,r_0)}$ , and consider  $G=H\circ\psi$ . Then the morphism  $\phi_G^1=\psi^{-1}\circ\phi_H^1\circ\psi$  rotates the disk  $\mathbb{D}_{(0,r_0)}$ .



• The following conjugation formulas for Cal and  $\sigma$  are useful. Denote by  $\sigma = \sigma_{\phi}$  to emphasize its dependence on morphism  $\phi$ .

ullet The following conjugation formulas for Cal and  $\sigma$  are useful. Denote by  $\sigma=\sigma_\phi$  to emphasize its dependence on morphism  $\phi$ .

### Proposition (Exercise)

For any  $\omega$ -preserving diffeomorphism  $\psi$  on  $\mathring{\mathbb{D}}$ ,

- $\operatorname{Cal}(\psi^{-1} \circ \phi \circ \psi) = \operatorname{Cal}(\phi);$
- $\sigma_{\psi^{-1}\circ\phi\circ\psi} = \sigma_{\phi}\circ\psi + u u\circ(\psi^{-1}\circ\phi\circ\psi)$ , where  $du = \psi^*\lambda \lambda$ .

ullet The following conjugation formulas for Cal and  $\sigma$  are useful. Denote by  $\sigma=\sigma_\phi$  to emphasize its dependence on morphism  $\phi$ .

### Proposition (Exercise)

For any  $\omega$ -preserving diffeomorphism  $\psi$  on  $\mathring{\mathbb{D}}$ ,

- $\operatorname{Cal}(\psi^{-1} \circ \phi \circ \psi) = \operatorname{Cal}(\phi);$
- $\sigma_{\psi^{-1}\circ\phi\circ\psi} = \sigma_{\phi}\circ\psi + u u\circ(\psi^{-1}\circ\phi\circ\psi)$ , where  $du = \psi^*\lambda \lambda$ .

In particular, for our example,  $u=\frac{1}{2}(x_0y-y_0x)$  on  $\mathbb{D}_{(0,r_0)}$ , where  $z_0=x_0+iy_0$ .

• The following conjugation formulas for Cal and  $\sigma$  are useful. Denote by  $\sigma=\sigma_\phi$  to emphasize its dependence on morphism  $\phi$ .

### Proposition (Exercise)

For any  $\omega$ -preserving diffeomorphism  $\psi$  on  $\mathring{\mathbb{D}}$ ,

- $\operatorname{Cal}(\psi^{-1} \circ \phi \circ \psi) = \operatorname{Cal}(\phi);$
- $\sigma_{\psi^{-1}\circ\phi\circ\psi} = \sigma_{\phi}\circ\psi + u u\circ(\psi^{-1}\circ\phi\circ\psi)$ , where  $du = \psi^*\lambda \lambda$ .

In particular, for our example,  $u = \frac{1}{2}(x_0y - y_0x)$  on  $\mathbb{D}_{(0,r_0)}$ , where  $z_0 = x_0 + iy_0$ . Moreover,

$$\sigma_{\phi} = \sigma_{\psi^{-1} \circ \phi \circ \psi} \circ \psi^{-1} + \underbrace{u \circ (\psi^{-1} \circ \phi) - u \circ \psi^{-1}}_{\text{hard to be precise}}.$$

• The following conjugation formulas for Cal and  $\sigma$  are useful. Denote by  $\sigma = \sigma_{\phi}$  to emphasize its dependence on morphism  $\phi$ .

### Proposition (Exercise)

For any  $\omega$ -preserving diffeomorphism  $\psi$  on  $\mathbb{D}$ ,

- $\operatorname{Cal}(\psi^{-1} \circ \phi \circ \psi) = \operatorname{Cal}(\phi)$ ;
- $\sigma_{\psi^{-1}\circ\phi\circ\psi}=\sigma_{\phi}\circ\psi+u-u\circ(\psi^{-1}\circ\phi\circ\psi)$ , where  $du = \psi^* \lambda - \lambda$ .

In particular, for our example,  $u = \frac{1}{2}(x_0y - y_0x)$  on  $\mathbb{D}_{(0,r_0)}$ , where  $z_0 = x_0 + iy_0$ . Moreover,

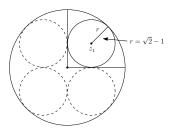
$$\sigma_{\phi} = \sigma_{\psi^{-1} \circ \phi \circ \psi} \circ \psi^{-1} + \underbrace{u \circ (\psi^{-1} \circ \phi) - u \circ \psi^{-1}}_{\text{hard to be precise}}.$$

An estimation:  $|u \circ (\psi^{-1} \circ \phi) - u \circ \psi^{-1}| \le r_0 |z_0| \le r_0$ , which implies that

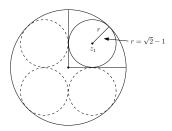
$$-k-r_0 \le \sigma_\phi \le r_0. \tag{2}$$



Consider sinkholes  $\mathbb{D}_i$  for i=1,...,4, sitting inside  $\mathbb{D}$  in the following symmetric way.



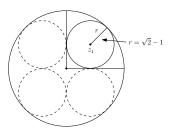
Consider sinkholes  $\mathbb{D}_i$  for i=1,...,4, sitting inside  $\mathbb{D}$  in the following symmetric way.



Consider the following Hamiltonian diffeomorphisms.

(1) 
$$\phi^+$$
 the rotation of  $\mathbb D$  by  $\frac{\pi}{2}$ . Profile:  $h(|z|^2) = \frac{\pi}{4}(1-|z|^2)$ .

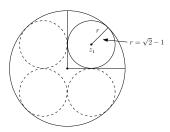
Consider sinkholes  $\mathbb{D}_i$  for i=1,...,4, sitting inside  $\mathbb{D}$  in the following symmetric way.



Consider the following Hamiltonian diffeomorphisms.

- (1)  $\phi^+$  the rotation of  $\mathbb D$  by  $\frac{\pi}{2}$ . Profile:  $h(|z|^2) = \frac{\pi}{4}(1-|z|^2)$ .
- (2)  $\phi_i^-$  the rotation of  $\mathbb{D}_i$  by  $-0.73\pi$ . (Caution: opposite direction!) Profile:  $h(|z|^2) = -0.365\pi \left(1 \frac{|z-z_i|^2}{r^2}\right)$ .

Consider sinkholes  $\mathbb{D}_i$  for i=1,...,4, sitting inside  $\mathbb{D}$  in the following symmetric way.



Consider the following Hamiltonian diffeomorphisms.

- (1)  $\phi^+$  the rotation of  $\mathbb{D}$  by  $\frac{\pi}{2}$ . Profile:  $h(|z|^2) = \frac{\pi}{4}(1-|z|^2)$ .
- (2)  $\phi_i^-$  the rotation of  $\mathbb{D}_i$  by  $-0.73\pi$ . (Caution: opposite direction!) Profile:  $h(|z|^2) = -0.365\pi \left(1 \frac{|z-z_i|^2}{r^2}\right)$ .

Denote

$$\phi = \phi^+ \circ \prod_{i=1}^4 \phi_i^-.$$

• Compute  $Cal(\phi)$  (recall that Cal is a homomorphism).

• Compute  $Cal(\phi)$  (recall that Cal is a homomorphism).

$$Cal(\phi) = Cal(\phi^+) + \sum_{i=1}^{4} Cal(\phi_i^-)$$

$$= \frac{\pi^2}{4} + 4(-0.365\pi \cdot \pi \cdot r^2) = -0.0004964\pi^2 < 0.$$

ullet Compute Cal( $\phi$ ) (recall that Cal is a homomorphism).

$$Cal(\phi) = Cal(\phi^{+}) + \sum_{i=1}^{4} Cal(\phi_{i}^{-})$$
$$= \frac{\pi^{2}}{4} + 4(-0.365\pi \cdot \pi \cdot r^{2}) = -0.0004964\pi^{2} < 0.$$

 $\bullet$  Compute  $\sigma=\sigma_{\phi}.$  We need the following composition formula

$$\sigma_{\phi_2 \circ \phi_1} = \sigma_{\phi_2} \circ \phi_1 + \sigma_{\phi_1}$$
 (Exercise).

• Compute  $Cal(\phi)$  (recall that Cal is a homomorphism).

$$Cal(\phi) = Cal(\phi^{+}) + \sum_{i=1}^{4} Cal(\phi_{i}^{-})$$
$$= \frac{\pi^{2}}{4} + 4(-0.365\pi \cdot \pi \cdot r^{2}) = -0.0004964\pi^{2} < 0.$$

ullet Compute  $\sigma=\sigma_{\phi}$ . We need the following composition formula

$$\sigma_{\phi_2 \circ \phi_1} = \sigma_{\phi_2} \circ \phi_1 + \sigma_{\phi_1}$$
 (Exercise).

Then we can compute

$$egin{aligned} \sigma_{\phi} &= \sigma_{\phi^+} \circ \left(\prod_{i=1}^4 \phi_i^-
ight) + \sigma_{\prod_{i=1}^4 \phi_i^-} \ &= \sigma_{\phi^+} \circ \left(\prod_{i=1}^4 \phi_i^-
ight) + \sum_{i=1}^4 \sigma_{\phi_i^-}. \end{aligned}$$

Though we can not explicitly describe  $\sigma_{\phi}$ , here are some observations.

Though we can not explicitly describe  $\sigma_{\phi}$ , here are some observations.

• By (2), we have an estimation. For any  $z \in \mathbb{D}$ ,

$$\sigma_{\phi}(z) \ge 0 + (-0.365\pi - (\sqrt{2} - 1)) = -1.56 > -\frac{\pi}{2}.$$

Though we can not explicitly describe  $\sigma_{\phi}$ , here are some observations.

• By (2), we have an estimation. For any  $z \in \mathbb{D}$ ,

$$\sigma_{\phi}(z) \ge 0 + (-0.365\pi - (\sqrt{2} - 1)) = -1.56 > -\frac{\pi}{2}.$$

• Since  $0 \notin \bigcup_{i=1}^4 \mathbb{D}_i$ ,  $\sigma_{\phi}(0) = \sigma_{\phi^+}(0) = \frac{\pi}{4} > 0$ .

Though we can not explicitly describe  $\sigma_{\phi}$ , here are some observations.

• By (2), we have an estimation. For any  $z \in \mathbb{D}$ ,

$$\sigma_{\phi}(z) \ge 0 + (-0.365\pi - (\sqrt{2} - 1)) = -1.56 > -\frac{\pi}{2}.$$

• Since  $0 \notin \bigcup_{i=1}^4 \mathbb{D}_i$ ,  $\sigma_{\phi}(0) = \sigma_{\phi^+}(0) = \frac{\pi}{4} > 0$ .

Recall that in Bramham's construction, (in order to get a free  $\mathbb{Z}$ -action), we consider a shifted action function

$$\tau = \sigma_{\phi} + \pi.$$

Though we can not explicitly describe  $\sigma_{\phi}$ , here are some observations.

• By (2), we have an estimation. For any  $z \in \mathbb{D}$ ,

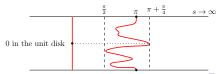
$$\sigma_{\phi}(z) \ge 0 + (-0.365\pi - (\sqrt{2} - 1)) = -1.56 > -\frac{\pi}{2}.$$

• Since  $0 \notin \bigcup_{i=1}^4 \mathbb{D}_i$ ,  $\sigma_{\phi}(0) = \sigma_{\phi^+}(0) = \frac{\pi}{4} > 0$ .

Recall that in Bramham's construction, (in order to get a free  $\mathbb{Z}$ -action), we consider a shifted action function

$$\tau = \sigma_{\phi} + \pi$$
.

A schematic picture of Bramham's solid torus (denoted earlier by M) is the following.



Closed Reeb orbit comes from two cases: (1) fixed point of  $\phi$  on  $\mathbb{D}$ ; (2) k-periodic points of  $\phi$  on  $\mathbb{D}$ .

Closed Reeb orbit comes from two cases: (1) fixed point of  $\phi$  on  $\mathbb{D}$ ; (2) k-periodic points of  $\phi$  on  $\mathbb{D}$ .

• For Case (1), the only fixed point of  $\phi$  is 0, and its period is  $\tau(0) = \sigma_{\phi}(0) + \pi \geq \pi$ .

Closed Reeb orbit comes from two cases: (1) fixed point of  $\phi$  on  $\mathbb{D}$ ; (2) k-periodic points of  $\phi$  on  $\mathbb{D}$ .

- For Case (1), the only fixed point of  $\phi$  is 0, and its period is  $\tau(0) = \sigma_{\phi}(0) + \pi \ge \pi$ .
- For Case (2), for any k-periodic points (where  $k \geq 2$ ), the corresponding closed orbit has its period equal to  $k\tau(z) = k(\sigma_{\phi}(z) + \pi) \geq k \cdot \frac{\pi}{2} \geq \pi$ .

Closed Reeb orbit comes from two cases: (1) fixed point of  $\phi$  on  $\mathbb{D}$ ; (2) k-periodic points of  $\phi$  on  $\mathbb{D}$ .

- For Case (1), the only fixed point of  $\phi$  is 0, and its period is  $\tau(0) = \sigma_{\phi}(0) + \pi \ge \pi$ .
- For Case (2), for any k-periodic points (where  $k \geq 2$ ), the corresponding closed orbit has its period equal to  $k\tau(z) = k(\sigma_{\phi}(z) + \pi) \geq k \cdot \frac{\pi}{2} \geq \pi$ .
- $\Rightarrow$  The conclusion is that  $T_{\min}(\alpha) \ge \pi$ .

Closed Reeb orbit comes from two cases: (1) fixed point of  $\phi$  on  $\mathbb{D}$ ; (2) k-periodic points of  $\phi$  on  $\mathbb{D}$ .

- For Case (1), the only fixed point of  $\phi$  is 0, and its period is  $\tau(0) = \sigma_{\phi}(0) + \pi \ge \pi$ .
- For Case (2), for any k-periodic points (where  $k \geq 2$ ), the corresponding closed orbit has its period equal to  $k\tau(z) = k(\sigma_{\phi}(z) + \pi) \geq k \cdot \frac{\pi}{2} \geq \pi$ .
- $\Rightarrow$  The conclusion is that  $T_{\min}(\alpha) \ge \pi$ .

The upshot is:

$$\begin{cases} \operatorname{vol}_{\alpha \wedge d\alpha}(S^3) = \pi^2 + \operatorname{Cal}(\phi) \\ \operatorname{Cal}(\phi) < 0 \\ T_{\min}(\alpha) \ge \pi \end{cases} \Rightarrow T_{\min}(\alpha)^2 > \operatorname{vol}_{\alpha \wedge d\alpha}(S^3).$$

• One can re-do the computation above by starting with a very narrow sector of  $\mathbb D$  and rotate it making it symmetric. Then the resulting  $\phi$  will be  $C^0$ -close to  $\mathbb 1_{\mathbb D}$  (and  $\alpha$  is  $C^0$ -closed to  $\alpha_0$ ).

- One can re-do the computation above by starting with a very narrow sector of  $\mathbb D$  and rotate it making it symmetric. Then the resulting  $\phi$  will be  $C^0$ -close to  $\mathbb 1_{\mathbb D}$  (and  $\alpha$  is  $C^0$ -closed to  $\alpha_0$ ).
- With higher regularity, the  $\alpha$  we constructed in this talk is far from  $\alpha_0$ . In fact, it is far from any **Zoll contact form**, i.e., all the Reeb orbits are closed and the periods are the same.

- One can re-do the computation above by starting with a very narrow sector of  $\mathbb D$  and rotate it making it symmetric. Then the resulting  $\phi$  will be  $C^0$ -close to  $\mathbb 1_{\mathbb D}$  (and  $\alpha$  is  $C^0$ -closed to  $\alpha_0$ ).
- With higher regularity, the  $\alpha$  we constructed in this talk is far from  $\alpha_0$ . In fact, it is far from any **Zoll contact form**, i.e., all the Reeb orbits are closed and the periods are the same. This is due to the following result.

### Theorem (Abbondandolo-Bramham-Hryniewicz-Salomão, 2018)

There exists a  $C^3$ -neighborhood  $\mathcal N$  of the space of Zoll contact forms on  $S^3$  such that for any  $\alpha \in \mathcal N$ ,

$$T_{\min}(\alpha)^2 \leq \operatorname{vol}_{\alpha \wedge d\alpha}(S^3).$$

The equality holds if and only if  $\alpha$  is Zoll.



- One can re-do the computation above by starting with a very narrow sector of  $\mathbb D$  and rotate it making it symmetric. Then the resulting  $\phi$  will be  $C^0$ -close to  $\mathbb 1_{\mathbb D}$  (and  $\alpha$  is  $C^0$ -closed to  $\alpha_0$ ).
- With higher regularity, the  $\alpha$  we constructed in this talk is far from  $\alpha_0$ . In fact, it is far from any **Zoll contact form**, i.e., all the Reeb orbits are closed and the periods are the same. This is due to the following result.

### Theorem (Abbondandolo-Bramham-Hryniewicz-Salomão, 2018)

There exists a  $C^3$ -neighborhood  $\mathcal N$  of the space of Zoll contact forms on  $S^3$  such that for any  $\alpha \in \mathcal N$ ,

$$T_{\min}(\alpha)^2 \le \operatorname{vol}_{\alpha \wedge d\alpha}(S^3).$$

The equality holds if and only if  $\alpha$  is Zoll.

Its proof runs our construction backwards, i.e., constructing an  $\omega$ -preserving diffeomorphism on  $\mathbb{D}$  from a contact form on  $S^3$ .



Three ways to transfer dynamics to geometry.

Three ways to transfer dynamics to geometry.

• Bramham's construction:  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega) \longrightarrow (S^3, \alpha)$  (which bounds a star-shaped domain in  $\mathbb{R}^4$ ).

Three ways to transfer dynamics to geometry.

- Bramham's construction:  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega) \longrightarrow (S^3, \alpha)$  (which bounds a star-shaped domain in  $\mathbb{R}^4$ ).
- Eliashberg-Polterovich's construction: given a positive loop of contactomorphisms  $\phi = \{\phi_t\}_{t \in S^1}$  on a Liouville-fillable contact manifold  $(X,\alpha)$ .

Three ways to transfer dynamics to geometry.

- Bramham's construction:  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega) \longrightarrow (S^3, \alpha)$  (which bounds a star-shaped domain in  $\mathbb{R}^4$ ).
- Eliashberg-Polterovich's construction: given a positive loop of contactomorphisms  $\phi = \{\phi_t\}_{t \in S^1}$  on a Liouville-fillable contact manifold  $(X,\alpha)$ . The following construction results in a contact star-shaped domain  $V(\phi) \subset \widehat{W} \times S^1$ ,

$$V(\phi) := \{(s, x, t) \in SX \times S^1 \mid s \cdot h(t, x) < 1\} \cup (Core \times S^1)$$

where h(t,x) is the contact Hamiltonian of  $\phi$ .

Three ways to transfer dynamics to geometry.

- Bramham's construction:  $\phi \in \operatorname{Ham}_c(\mathring{\mathbb{D}}, \omega) \longrightarrow (S^3, \alpha)$  (which bounds a star-shaped domain in  $\mathbb{R}^4$ ).
- Eliashberg-Polterovich's construction: given a positive loop of contactomorphisms  $\phi = \{\phi_t\}_{t \in S^1}$  on a Liouville-fillable contact manifold  $(X,\alpha)$ . The following construction results in a contact star-shaped domain  $V(\phi) \subset \widehat{W} \times S^1$ ,

$$V(\phi) := \{(s, x, t) \in SX \times S^1 \mid s \cdot h(t, x) < 1\} \cup (\operatorname{Core} \times S^1)$$

where h(t,x) is the contact Hamiltonian of  $\phi$ .

• Usher's tube construction: given a Liouville domain  $(W,\lambda)$  and an autonomous Hamiltonian function  $H:W\to\mathbb{R}$  satisfying certain "positivity condition", the following construction results in another Liouville domain,

$$W_H := \{(w, z) \in W \times \mathbb{C} \mid \pi |z|^2 \le H(w)\}.$$

